

Item	Description Modify by button ▲ or ▼	Range Modify by button ▲ or ▼	Default Value	
			Default (3)	Default (6)
Pn 24	Multi-segment speed 5 frequency	000.10 Hz—400.00Hz	50	50
Pn 25	Multi-segment speed 6 frequency	000.10 Hz—400.00Hz	60	60
Pn 26	Multi-segment speed 7 frequency	000.10 Hz—400.00Hz	70	70
Pn 27	Point move frequency	000.10 Hz—400.00Hz	10Hz	10Hz
Pn 28	Choice of relay output	1—6	3	3
Pn 29	2nd acceleration time	000.01S—650.00S	2S	2S
Pn 30	2nd deceleration time	000.01S—650.00S	2S	2S
Pn 31	2nd deceleration stop frequency	000.01Hz—400.00Hz	1Hz	1Hz
Pn 32	Parameter management	1—6	1	1
Pn 33	Software version	32029	*****	*****
Pn 34	Auto recover while lost power suddenly	0—99Hz	0	0
Pn 35	Production date	*	*****	*****

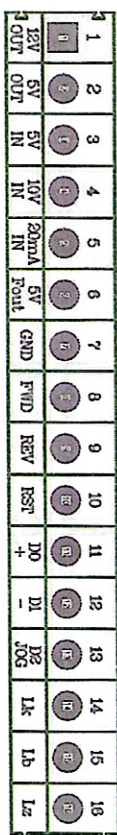
Please refer Chapter 7 for detail description of each item

Remark: If over-voltage happens during deceleration, it will stop.

Note:

If over-voltage happens during deceleration, inverter will stop deceleration until the voltage goes back to normal level. If better deceleration is needed, please switch to inverter with braking.

## Chapter 6 Description of Control Ports



Port name	Port Description
12V OUT	12V output, with maximum current 200mA.
5V OUT	5V output, with maximum current 50mA.
5V IN	5V input, analog input, with maximum effective voltage 5V, no more than 6V
10V IN	10V input, analog input, with maximum effective voltage 10V, no more than 12V
20mA IN	20mA input, analog input, with maximum effective current 20mA, no more than 25mA
5V Fout	Frequency signal output, maximum output voltage 5V
GND	Power source ground 0V.
FWD	External clockwise rotation input
REV	External anticlockwise rotation input
RST	External reset signal
D0 +	Multi-segment speed D0 input, external “+” signal means clockwise point move input
D1 -	Multi-segment speed D1 input, external “-” signal means anticlockwise point move input
D2 JOG	Multi-segment speed D2 input, external enable signal input
Lk	Relay ON
Lb	Relay OFF
Lz	Relay ON/OFF